1	Correcting for Unreliability and Partial Invariance: A Two-Stage Path Analysis Approach
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In path analysis, using composite scores without adjustment for measurement unreliability and violations 23 of factorial invariance across groups leads to biased estimates of path coefficients. Although joint modeling 24 of measurement and structural models can theoretically yield consistent structural association estimates, 25 the estimation of a model with many variables is often impractical in small samples. A viable alternative is 26 two-stage path analysis (2S-PA), where researchers first obtain factor scores and the corresponding 27 individual-specific reliability coefficients, and then use those factor scores to analyze structural associations 28 while accounting for their unreliability. The current paper extends 2S-PA to also account for partial 29 invariance. Two simulation studies show that 2S-PA outperforms joint modeling in terms of model 30 convergence, the efficiency of structural parameter estimation, and confidence interval coverage, especially 31 in small samples and with categorical indicators. We illustrate 2S-PA by reanalyzing data from a 32 multiethnic study that predicts drinking problems using college-related alcohol beliefs. 33 Keywords: two-stage path analysis, factorial invariance, partial invariance, measurement error, 34

35 factor scores

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³⁶ Word count: 7,366

Abstract

37 Correcting for Unreliability and Partial Invariance: A Two-Stage Path Analysis Approach

Over the past two decades, there has been a tremendous increase in research evaluating the 38 measurement invariance of instruments in psychology. If measurement invariance—the condition that an 30 instrument measures the same construct the same way across groups—is violated, the observed composite 40 scores are not on the same metric across groups, and thus group comparisons using those scores are not 41 meaningful. That said, when only part of the items in an instrument is noninvariant—meaning that the 42 instrument is partially invariant—researchers can still obtain valid statistical results by jointly modeling 43 partial invariance and the structural associations among the latent constructs see Hsiao and Lai, 2018. 44 However, the joint modeling approach is computationally demanding as it requires including all 45 measurement indicators in the analysis, even when researchers only have a relatively simple structural 46 model. Also, when the sample size is relatively small, joint modeling often suffers from issues of 47 convergence and nonadmissible solutions (Rosseel, 2020). As discussed later in this paper, in practice, 48 researchers rarely use the joint modeling approach to adjust for partial invariance, but continue to use 49 composite scores (e.g., sum scores or mean scores) following invariance analyses. 50

However, using composite scores without any adjustment is potentially problematic in two regards.
First, the presence of noninvariant items can systematically bias analysis results, such as regression
coefficients or mean comparisons. Second, using composite scores assumes that they do not contain
measurement error, meaning they are perfectly reliable, which is rare, if possible, in behavioral and social
sciences. It is well known in the literature that ignoring measurement unreliability leads to biased
regression coefficients (e.g., Carroll et al., 2006; Cole & Preacher, 2014; Ledgerwood & Shrout, 2011).

As an alternative, recently, there has been a renewed interest in using psychometric-model-based 57 factor scores (e.g., Estabrook & Neale, 2013; McNeish & Wolf, 2020), which adjust for partial invariance to 58 put the latent variables on a common or approximately common metric (e.g., Curran & Hussong, 2009). 59 However, like sum scores, factor scores are also not perfectly reliable, so using them in analyses without 60 correction for measurement error will still lead to biased coefficients, with the magnitude of bias depending 61 on the reliability of the factor scores (Croon, 2002; Levy, 2017). Also, as shown later, when partial 62 invariance exists, not every way of computing factor scores results in scores on the same metric, so further 63 adjustment is needed. 64

Two general and related approaches to account for measurement error when using estimated scores (i.e., composite or factor scores) are of interest. In the first approach, researchers first obtain naive path coefficients by treating the estimated scores as the true latent variable scores. Correction factors are obtained based on the relation between the estimated scores and the latent variable in the measurement

model, and then applied to the naive coefficients to obtain corrected coefficients. The correction factors are 69 usually functions of score reliability. Fan (2003) discussed an example with two latent variables, η_X and η_Y . 70 When the two latent variables were measured by multi-item scales that give composite scores X and Y, 71 respectively, one can estimate the true correlation between η_X and η_Y as $r_{XY}/\sqrt{\rho_X\rho_Y}$, where r_{XY} is the 72 correlation between the composite scores and ρ_X and ρ_Y are the composite reliability of X and Y, 73 respectively. Croon (2002) showed how this approach can be used when factor scores are used instead, with 74 slightly more involved correction formulas that are functions of factor loadings and latent variances. The 75 method of Croon was further elaborated in the method of factor score path analysis (Devlieger & Rosseel, 76 2017; Devlieger et al., 2016), which also includes corrected standard errors and inferences for the corrected 77 path coefficients. 78

The second approach is the reliability adjustment method, which treats the composite scores or 79 factor scores as single indicators of latent variables and constrains the reliability of these indicators to 80 either known values or estimates from the data (e.g., Bollen, 1989; Hsiao et al., 2018, 2021; Kwok et al., 81 2016; Savalei, 2019). However, both the correction factor approach and the reliability adjustment method 82 generally assume constant measurement error variance for the whole sample, which is likely violated when 83 only partial invariance holds or when indicators are binary or ordinal. Thus, previous methods for handling 84 measurement error only address parameter bias due to unreliability, and may still yield inconsistent 85 estimates due to unadjusted partial invariance. A more general approach to reliability adjustment is the 86 two-stage path-analysis (2S-PA) with definition variables method by M. H. C. Lai and Hsiao (2021), which 87 accounts for the unreliability in factor scores even when reliability is not constant across observations. 88 While previous studies have only focused on the reliability adjustment aspect of 2S-PA, the current paper 89 shows how researchers can use 2S-PA to adjust for both partial invariance and unreliability for continuous 90 and discrete indicators. We also report evidence from two simulation studies showing that 2S-PA has fewer 91 convergence issues and more accurate estimation and inference in small samples than the joint structural 92 equation modeling (SEM) approach. 93

94 Multiple-Group Joint SEM

In behavioral sciences, joint SEM modeling is the recommended approach for incorporating imperfect measurement when analyzing relations among latent variables (e.g., Cole & Preacher, 2014). In SEM, theoretical constructs, such as depression and cognitive ability, are represented as latent variables, ηs, and each of them is measured by one or more observed indicators. When both the measurement (between ηs and their indicators) and the structural (among the ηs) models are correctly specified, joint SEM modeling with maximum likelihood estimation yields consistent and asymptotically efficient ¹⁰¹ structural coefficient estimates (e.g., Bollen, 1989). In the case of partial invariance, where some

- $_{102}$ measurement parameters differ across a grouping variable G, one common approach is to use a
- ¹⁰³ multiple-group analysis that places equality constraints on only those measurement parameters found
- ¹⁰⁴ invariant across groups. Specifically, denote the measurement model among p observed indicators, \mathbf{y} , and q

latent variables, η , as $f(\mathbf{y}|\boldsymbol{\eta}, \boldsymbol{\omega})$ with measurement parameters $\boldsymbol{\omega}$, and assume that the structural model

- ¹⁰⁶ can be characterized as a linear model. Assuming that each observation $i = 1, \ldots, n_g$ in group g is
- ¹⁰⁷ independent, the multiple-group joint SEM can be described by the model

with equality constraints on a subset of $\boldsymbol{\omega}_g$ across some groups g_1, g_2 , and so forth. In the structural model, $\boldsymbol{\alpha}$ contains the q latent regression intercepts, \mathbf{B} is a $q \times q$ matrix of structural coefficients, and ζ_{ig} is a vector of disturbances with the standard assumption $\mathrm{E}(\zeta_{ig}) = \mathbf{0}$.¹

As an example, consider a model with $\mathbf{y} = [y_1, \dots, y_6]^{\top}$ and $\mathbf{\eta} = [\eta_X, \eta_2]$, where η_2 is observed 111 (similar to Figure 1). Assuming a linear factor model linking **y** and η_1 such that $y_j = \nu_j + \lambda_j \eta_1 + \varepsilon_j$ with 112 $\boldsymbol{\varepsilon} \sim N(\mathbf{0}, \boldsymbol{\Theta})$ and j indexing indicators, the measurement parameters are $\boldsymbol{\omega} = (\mathbf{v}, \boldsymbol{\lambda}, \boldsymbol{\Theta})$ and there is one 113 structural path coefficient in $\mathbf{B} = \begin{bmatrix} 0 & 0 \\ \beta_1 & 0 \end{bmatrix}$. When there are multiple groups, a prerequisite to compare 114 structural coefficients (e.g., α and **B**) across groups is that ω is sufficiently invariant, which can be 115 examined by analyzing factorial invariance (Meredith, 1964)—measurement invariance under a factor 116 model—of the items. If the items all have the same number of underlying factors (one in this example), 117 and the pattern of how the items and the underlying factors are linked is the same across groups, the 118 condition of configural invariance (Horn & McArdle, 1992; Meredith, 1964) is met. Furthermore, the items 119 are considered metric invariant if $\lambda_1 = \lambda_2$, scalar invariant if, additionally, $\mathbf{v}_1 = \mathbf{v}_2$, and strict invariant if 120 also $\Theta_1 = \Theta_2$ so that all measurement parameters are equal (e.g., Widaman & Reise, 1997). If some 121 elements of $\boldsymbol{\omega}$ are not invariant across groups, a partial invariance model should be specified so that only 122 the invariant subset of $\boldsymbol{\omega}$ is constrained equal across groups in the joint SEM approach (e.g., Byrne et al., 123 1989; Hsiao & Lai, 2018). 124

Although the multiple-group joint SEM approach (hereafter JSEM) is very flexible, as discussed in the previous literature (e.g., Croon, 2002; Devlieger et al., 2016; M. H. C. Lai & Hsiao, 2021; McNeish &

¹ Note that we could allow **B** to be group-specific to represent $G \times \eta$ interactions; however, based on our small literature review (described later in the paper), researchers rarely specified such an interaction, so in the current paper we mainly focus on analyses with a common **B**.

Wolf, 2020; Rosseel & Loh, 2021), it does present several challenges, both in terms of computation and 127 usage in practice. First, JSEM requires specifying a large model even when the structural model is 128 relatively small. Consider a structural model with three latent constructs, each measured by 10 observed 129 indicators, resulting in a total of 30 observed variables. Although a researcher may only be interested in 130 three or four structural coefficients, JSEM would need estimations of hundreds of measurement parameters. 131 Not only is the large model size difficult for researchers to keep track of and identify misfits, but it also 132 makes JSEM more prone to convergence failures in optimization algorithms and inflated Type I error rates 133 of the structural coefficients (Devlieger & Rosseel, 2017; Kelcey, 2019; M. H. C. Lai & Hsiao, 2021; Rosseel, 134 2020). Second, for models not assuming a multivariate normal likelihood function, such as when the 135 observed indicators are ordinal or categorical, estimating JSEM models (e.g., with numerical integration) is 136 computationally demanding and not feasible even with only a few latent dimensions (Pritikin et al., 2018). 137 Third, with joint modeling, misspecifications in the measurement models can affect parameter estimates in 138 the structural model. Compared to multistage methods like 2S-PA, structural parameters with JSEM are 139 more susceptible to misspecifications in the measurement models (Devlieger & Rosseel, 2017; M. H. C. Lai 140 & Hsiao, 2021). The other side of the same coin—that misspecifications in the structural model can affect 141 parameter estimates in the measurement models—is equally troubling. It leads to interpretational 142 confounding (Bollen & Maydeu-Olivares, 2007; Burt, 1976; Levy, 2017), where the operationalization of the 143 latent construct is different in different structural models, even with the same data. 144

¹⁴⁵ A Brief Review on the Use of Joint Modeling Following Invariance Evaluation

Given the conceptual and computational challenges of SEM, researchers often use composite or 146 factor scores to analyze structural models, even after they conduct extensive psychometric explorations 147 such as measurement invariance analysis. For example, in a review of articles published in the Journal of 148 Applied Psychology and Personality and Individual Differences in 2020, we identified 30 articles that either 149 tested measurement invariance (n = 26) or cited external evidence for measurement invariance (n = 4). 150 Among them, 26 articles concluded with configural (n = 2), metric (n = 13), scalar (n = 10), or strict (n = 10)151 1) invariance; the remaining articles either reported noninvariance (n = 3) or provided insufficient 152 information about test results (n = 1). 153

Even though many of the articles we reviewed already performed invariance analyses, the majority (n = 16) still used composite scores for subsequent statistical analyses, while others used either factor scores (n = 1) or JSEM (n = 8). For the articles that used composite scores, only four supported scalar or strict invariance (i.e., the minimum requirement for composite scores to be comparable across groups; Putnick & Bornstein, 2016), whereas eight established only metric invariance, two showed only configural ¹⁵⁹ invariance, and two concluded with measurement noninvariance.

When comparing the sample sizes of articles using different methods, those using composite scores had a median of two groups with median $\bar{n} = 377$ per group, whereas the ones using JSEM had a median of three groups with median $\bar{n} = 451$ per group. While JSEM requires a relatively large sample size (e.g., n> 500 or 2000; Rosseel, 2020), studies with fewer samples might adopt alternative methods for group comparisons or regression analyses.

Thus, this brief review shows that researchers commonly used composite scores in subsequent analyses, even when measurement invariance was violated. Ignoring violations of measurement invariance and imperfect reliability may result in biased statistical results. Therefore, alternative methods that are easy to specify while still producing consistent estimates are desirable. The current paper will focus on 2S-PA as one of those methods.

170 Two-Stage Path Analysis (2S-PA) With Definition Variables

Building on the literature of errors-in-variables models (e.g., Carroll et al., 2006; Meijer et al., 171 2021), M. H. C. Lai and Hsiao (2021) proposed 2S-PA as an alternative to JSEM. In the first stage of 172 2S-PA, researchers obtain factor scores for each observation *i* on each latent construct *m*, $\tilde{\eta}_{mi}$, and their 173 estimated reliability, $\tilde{\rho}_{\tilde{\eta}mi}$. In addition, in order to account for noninvariant measurement parameters, the 174 factor scores should be obtained from partial invariance models where η is calibrated to be on the same 175 metric. Unlike JSEM, where the same software and estimation method are used for all measurement and 176 structural models, with 2S-PA, one can use different software for obtaining factor scores for different 177 constructs, as long as consistent estimates of factor score reliability can be obtained for each observation. 178 For example, one can use a specialized item response model for factor scores of one construct and a 179 network model for centrality scores for another construct, as long as they are appropriate models to 180 operationalize variables in their hypothesized model. In the second stage of 2S-PA, full-information 181 maximum likelihood is used to estimate the structural model: 182

Measurement:
$$\tilde{\boldsymbol{\eta}}_i = \Lambda_i^* \boldsymbol{\eta}_i^* + \boldsymbol{\varepsilon}_i^*$$
,
Structural: $\boldsymbol{\eta}_i^* = \boldsymbol{\alpha}^* + \mathbf{B}^* \boldsymbol{\eta}_i^* + \boldsymbol{\zeta}_i^*$ (2)

where Λ_i^* is a loading matrix and is assumed diagonal when each factor score variable is an indicator of only one latent variable, $\xi_i^* \sim N(\mathbf{0}, \Psi^*)$ and $\varepsilon_i^* \sim N(\mathbf{0}, \Theta_i^*)$. When the factor scores are calibrated to the same metric across individuals and groups, one can set $\Lambda_i^* = \mathbf{I}$ for identification; however, when they are not calibrated, $\Lambda_i^* \neq \mathbf{I}$ should be specified so that $\mathbf{\eta}^*$ is on the same metric across groups, as discussed below for ¹⁸⁷ composite scores and factor scores obtained with the regression method. The 2S-PA model further ¹⁸⁸ accounts for the unreliability of $\tilde{\eta}_m$ by setting the ratio of true score variance $(\lambda^*_{mi} \operatorname{Var}[\eta_m^*])$ and the total ¹⁸⁹ variance (i.e., true score variance + error variance) to the reliability value estimated in stage 1, such that

$$\frac{\lambda_{mi}^{*2} \operatorname{Var}(\eta_m^*)}{\theta_{mi}^* + \lambda_{mi}^{*2} \operatorname{Var}(\eta_m^*)} = \tilde{\rho}_{\tilde{\eta}mi}.$$
(3)

¹⁹⁰ Note that we use η^* in equation (2), as they can be on a different metric than η in the first stage ¹⁹¹ estimation; thus, the unstandardized parameter estimates from JSEM and 2S-PA are generally not ¹⁹² comparable. M. H. C. Lai and Hsiao (2021) showed that in single-group analyses, one should compare the ¹⁹³ standardized coefficients; as discussed later, when the analyses involve multiple groups, additional ¹⁹⁴ adjustments on the standardized coefficients are needed to place the parameter estimates from ¹⁹⁵ multiple-group JSEM and single-group 2S-PA on approximately the same unit.

The constraints in 2S-PA are similar to those discussed in the reliability adjustment literature (e.g., Hsiao et al., 2018; Meijer et al., 2021; Savalei, 2019), except that it allows the reliability to be observation-specific, which accommodates ordered categorical items and violations of strict factorial invariance. It thus requires software programs that support observation-specific constraint variables, such as OpenMx (via definition variables; Neale et al., 2016) and Mplus (via constraint variables; Muthén & Muthén, 1998–2017).

202 2S-PA With Various Estimated Scores

Below, we consider how 2S-PA can be applied to three commonly computed scores for continuous 203 indicators under a factor model: regression factor scores (Thomson, 1935), Bartlett factor scores (Bartlett, 204 1937), and sum scores. In each case, the estimated scores are linear combinations of the observed item 205 scores such that $\tilde{\eta}_{ig} = \mathbf{A}_g \mathbf{y}_{ig}$, where \mathbf{A}_g is the factor score matrix. For simplicity, we drop the mean 206 structure in the discussion as mean differences across groups do not affect the path coefficients when the 207 group membership is included as a covariate in the second stage analysis (Curran et al., 2018). We also 208 assume that the items are unidimensional, so only one latent variable is involved. As the factor model 209 implies $\mathbf{y}_{ig} = \boldsymbol{\lambda}_g \eta_{ig} + \varepsilon_{ig}$, we have $\tilde{\eta}_{ig} = \mathbf{A}_g \boldsymbol{\lambda}_g \eta_{ig} + \mathbf{A}_g \varepsilon_{ig} = \boldsymbol{\lambda}_g^* \eta_{ig} + \varepsilon_i^*$. 210

As such, the reliability of the estimated scores is $(\mathbf{A}_g \boldsymbol{\lambda}_g)^2 \boldsymbol{\psi}_g / [(\mathbf{A}_g \boldsymbol{\lambda}_g)^2 \boldsymbol{\psi}_g + \mathbf{A}_g \Theta_g \mathbf{A}_g^{\top}]$, where $\boldsymbol{\psi}_g$ is the variance of η_g and Θ_g is the unique factor covariance matrix. When factorial invariance does not hold across groups, generally $\mathbf{A}_g \boldsymbol{\lambda}_g$ is different for different gs, so the estimated scores are on different metrics across groups. Therefore, the second stage of 2S-PA needs to incorporate information of $\mathbf{A}_g \boldsymbol{\lambda}_g$ when setting the loading of $\tilde{\eta}$ on η^* so that η^* is calibrated to the same metric.

As shown in Table 1, for both the regression factor scores and the sum scores, the loading (λ^*) of $\tilde{\eta}$ 216 on η depends on λ_g , so the scores are on different metrics when metric invariance is violated. Therefore, in 217 2S-PA, λ^* needs to be group-specific by setting the loading parameter as a definition/constraint variable. 218 On the other hand, the Bartlett scores are calibrated to be on the same unit as the latent variable with 219 $\lambda^* = 1$, so group-specific loading is not needed for 2S-PA. Also, regression scores are shrinkage estimates, 220 meaning they have a smaller variance when reliability is low (note that $\lambda^* = \rho_{\bar{n}}$), whereas Bartlett scores 221 are not. For sum scores, $\rho_{\tilde{\eta}}$ is the familiar ω reliability for composite scores (McDonald, 1999; Raykov, 222 1997). In Study 1, we evaluate the performance of 2S-PA with these three types of estimated scores for 223 continuous items. 224

For categorical items, sum scores are generally not appropriate as the items are not intervally scaled. As discussed in Hoshino and Bentler (2013), the expected a posteriori (EAP) scores are analogous to the regression factor scores, whereas maximum likelihood estimates of η are analogous to the Bartlett factor scores.

²²⁹ Within-Group Standardization and Grand Standardization

Structural parameter estimates depend on the assigned metrics of the latent variables. Because 230 JSEM and 2S-PA use observed variables on different units, the unstandardized parameter estimates are 231 generally not comparable. One solution is to look at the standardized coefficients, namely, the transformed 232 **B** coefficients when all η s have unity variance. However, in a multiple-group analysis (e.g., multiple-group 233 SEM), coefficients are often standardized using the within-group SD for η_m ($\sigma_{\eta mg}$), whereas in single-group 234 analysis with groups pooled into one analytic sample (e.g., in 2S-PA), coefficients are standardized using 235 the grand, or total, $SD(\sigma_{\eta m})$. Let $\mu_{\eta m1}, \ldots, \mu_{\eta mG}$ be the latent means of η_m across groups and n_1, \ldots, n_G 236 be the respective sample sizes with $\sum_{g=1}^{G} n_g = N$, then one can show that the grand SD is related to the 237 within-group SD in the equation (dropping the η_m subscript for better readability) 238

$$\sigma^{2} = \frac{1}{N} \sum_{g=1}^{G} n_{g} [\sigma_{g}^{2} + (\mu_{g} - \mu)^{2}], \qquad (4)$$

where $\mu = \sum_{g=1}^{G} n_g \mu_g / N$ is the grand mean. While researchers may prefer one way of standardization or the other in applied research, in simulation studies or research syntheses where different methods are compared, the coefficients are comparable only when converted to the same *SD* unit. 251

In the remainder of the current paper, we report two simulation studies comparing JSEM and 243 2S-PA in the presence of partial invariance. In Study 1, we use a simple latent regression model in which 244 only the predictor contains measurement error and partial invariance. In Study 2, we use a more complex 245 mediation model involving three constructs, wherein both the mediator and the outcome contain 246 measurement error and partial invariance. In addition, Study 2 also involves data with binary indicators. 247 The two simulation studies cover balanced and unbalanced sample sizes across two groups. We then 248 provide an example using data from a published paper illustrating how researchers can use 2S-PA following 249 evidence of partial invariance. We conclude with some future research directions for 2S-PA. 250

Study 1

In Study 1, we compare two approaches without reliability adjustment: sum-score path analysis 252 (PA) and factor score path analysis (FS-PA, with regression factor scores), with five approaches that adjust 253 for unreliability: Croon's correction (Croon), JSEM, and three 2S-PA methods, for estimating a regression 254 coefficient. We examined three variations of 2S-PA that use (a) regression factor scores, (b) Bartlett factor 255 scores, and (c) sum scores. In the data generating model, the latent predictor, X, is measured by six 256 indicators with partial invariance across two groups (G = 1 and 2). We generate data with four levels of 257 sample size for Group 1 ($n_1 = 50, 100, 500, 1000$), and the data is either balanced ($n_2 = n_1$) or unbalanced 258 $(n_2 = 0.6n_1)$. The average loading for Group 1 has two levels to represent situations of low reliability 259 (average loading = 0.7; composite reliability = .49 and .61 for Groups 1 and 2) and moderate reliability 260 (average loading = 1.0; composite reliability = .71 and .77 for Groups 1 and 2).² Figure 1 shows the data 261 generating values of the model parameters, where Group 2 has larger loadings on items 2 and 5. In 262 addition, items 4 and 5 have different intercepts, and items 4 and 6 have different unique variances. The 263 two groups also have different means and variances of η_X . To resemble minor misspecification in the 264 measurement model, we follow the suggestion by MacCallum and Tucker (1991) to add minor common 265 variances among the indicators, which results in covariances of magnitudes between -0.356 and 0.356 (i.e., 266 10% of the observed indicator variance in Group 1). For each condition, we simulated 2,500 replications 267 using R. 268

The unstandardized regression coefficient b_1 is manipulated to either 0 or 0.5 for both groups (i.e., no $\eta_X \times G$ interaction). To account for the above-mentioned metric incomparability issue in the estimated coefficients, we obtained the regression coefficient with η_X standardized using the grand SD of X. When b_1

 $^{^{2}}$ The composite reliability for sum scores is computed using the same formula as presented in Table 1 (see also Raykov, 1997).

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= 0.5, the standardized coefficient is $\beta_1 \approx 0.54$ (unbalanced samples) and 0.56 (balanced samples), whereas 272 when $b_1 = 0$, β_1 is also zero. All data generation is carried out in R. The package OpenMx (Neale et al., 273 2016) is used to obtain the grand-standardized regression coefficient using composite scores of X (i.e., PA, 274 which ignores noninvariance and unreliability), factor scores of X (i.e., FS-PA, which adjusts for partial 275 invariance but not unreliability), Croon's correction (see supplemental material for implementation 276 details), JSEM, and 2S-PA methods. For each condition and method, we evaluated the raw bias and root 277 mean squared error (RMSE) in estimating β_1 , as well as the relative standard error bias and the coverage 278 of the 95% confidence interval (CI). The full R script for the simulation can be found in the supplemental 279 materials (https://github.com/marklhc/2spa-inv-supp/). 280

For all conditions, the convergence rates were 99% or above; we only observed some estimation 281 issues in small-sample, low-reliability conditions for JSEM and 2S-PA; in some replications, there were 282 problems obtaining likelihood-based CI for 2S-PA. As shown in Tables 2 and 3, the impact of unequal ns 283 across groups was small. The results for PA and FS-PA were highly similar, except that FS-PA had higher 284 RMSEs and larger SE biases in small-sample, low-reliability conditions. Croon's correction performed 285 slightly worse than 2S-PA methods for most conditions in terms of bias. When $b_1 = \beta_1$ (standardized 286 coefficient) = 0, the estimates for all methods were essentially unbiased (with $|\text{bias}| \leq 0.01$). When $b_1 = 0$ 287 and $\beta_1 = 0$, JSEM and 2S-PA with sum scores (no bigger than 0.02 in absolute values) had the least bias, 288 while PA and FS-PA generated larger biases up to -0.15. 2S-PA with regression scores and Bartlett scores 289 showed downward bias in small samples (-0.07 for regression scores; -0.06 for Bartlett scores), but improved 290 with larger samples. For RMSE, PA performed the best when estimating a zero coefficient as there was no 291 attenuation due to unreliability; 2S-PA methods performed slightly better than JSEM for estimating a zero 292 coefficient and were virtually identical to JSEM across other conditions. In small-sample, low-reliability 293 conditions, 2S-PA with sum scores performed best in terms of RMSE. 294

When the reliability was relatively high, all methods gave acceptable standard errors, and all 295 methods except PA and FS-PA had acceptable CI coverage; the latter two had suboptimal coverage when 296 $\beta_1 \neq 0$, because their estimated coefficients were attenuated due to unreliability. When reliability was low, 297 the standard errors with JSEM were severely underestimated (up to -71.91%), and coverage was 298 suboptimal (< 92%) when the sample size was small; FS-PA and 2S-PA with regression and with Bartlett 299 scores had substantial bias in the estimated standard errors and undercoverage for nonzero true coefficients 300 in small samples, probably due to some instability in factor score estimation; Croon's correction performed 301 better than 2S-PA in terms of SE bias, but had worse coverage rates for low-reliability, small-sample 302 conditions. Overall, 2S-PA with sum scores performed well for all conditions; JSEM and 2S-PA were 303

similar and performed best for conditions with large sample sizes and relatively high reliability. When
comparing 2S-PA methods with regression scores and with Bartlett scores, they were generally similar,
with the former giving slightly better coverage rates overall.

The results of Study 1 show that 2S-PA and JSEM are both effective in accounting for both partial invariance and unreliability when sample sizes are large or when score reliability is above .70. Also, 2S-PA seems to give more efficient estimates and control the Type I error rate better. In small-sample or low-reliability situations with continuous indicators, Study 1 shows that 2S-PA with sum scores can be used for valid inferences and better estimation efficiency. The difference between 2S-PA and JSEM may be more prominent with more complex models, as shown in Study 2.

Study 2

As 2S-PA fits a simpler model in each step, compared to JSEM, we expect that it shows more 314 benefits in a more complex model, particularly when some of the indicators for the latent variables are 315 categorical. In Study 2, we consider a mediation model with a binary treatment variable X and with both 316 the mediator η_M and the outcome η_Y variables measured with errors. Both η_M and η_Y showed 317 noninvariance with respect to a grouping variable G. As shown in Figure 2, there were six indicators for η_M 318 and 16 indicators for η_Y . For the indicators of η_M , the population values of loadings, intercepts, and unique 319 variances were the same as those in the high-reliability condition in Study 1. For the indicators of η_Y , we 320 simulated them to be binary items following a 2-parameter normal ogive item response model such that 321

$$y_j^* = \lambda_{Yj} \eta_Y + \varepsilon_{Yj}$$
$$y_j = \begin{cases} 1 & y_j^* > \tau_j \\ 0 & \text{otherwise} \end{cases}$$

with $\varepsilon_{Yj} \sim N(0,1)$; λ s are the loading parameters analogous to those in the factor model, and τ s are the 322 thresholds. The population values of the measurement parameters were taken from a real-data abstract 323 reasoning test example in Embretson and Reise (2000, Table 4.2, p. 69), with loadings between 0.465 to 324 0.958 and item difficulties between -2.118 to 1.061 for Group 1. Items 1, 5, 9 were simulated to have 325 noninvariant loadings (magnitude = 0.118 to 0.294), and items 2, 5, 8 were simulated to have noninvariant 326 thresholds (magnitude = 0.3 to 0.5). The exact values can be found in the simulation code. The test 327 information for the η_Y indicators was above 1.81 for η_Y between -2 and 2, with peak information of 4.29 for 328 Group 1; it was similar for Group 2 (above 1.74 for $\eta_Y \in [-2, 2]$, peak = 4.42). 329

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Similar to Study 1, we added minor common variances among the indicators of η_M and η_Y ,

resulting in unique correlations in the range [-0.1, 0.1]. The sample sizes were equal across the two levels of G, with conditions of n = 50, 100, 300, 1,000 per group.

For both groups, we had the following structural model:

$$\eta_M = \alpha_M + \beta_1 X + \zeta_M$$
$$\eta_Y = \alpha_Y + \beta_2 X + \beta_3 \eta_M + \zeta_Y.$$

We allowed α_M and α_Y to be group-specific to represent main effects of G on η_M and η_Y , but there were no 334 group-related interactions. The population values were $\alpha_M = 0$ and 0.2, and $\alpha_Y = 0$ and 0.3, respectively 335 for G = 1 and 2; also, for all conditions, we fixed $\beta_2 = 0.3$. There were four conditions for the values β_1 336 and β_3 , including (a) $\beta_1 = \beta_3 = 0$, (b) $\beta_1 = 0.5$, $\beta_3 = 0$, (c) $\beta_1 = 0$, $\beta_3 = 0.3$, and (d) $\beta_1 = 0.5$, $\beta_3 = 0.3$. 337 Note that the indirect effect of X on η_Y was $\beta_1\beta_3 = 0$ for (a), (b), and (c), and was 0.15 for (d). The values 338 of $\operatorname{Var}(\zeta_M)$ and $\operatorname{Var}(\zeta_Y)$ were chosen such that the grand variances of η_M and η_Y are both one, so that the 339 grand-standardized coefficients (i.e., using the total SD without group memberships) and the 340 unstandardized coefficients were the same. 341

We compared multiple-group JSEM, path analysis with factor scores (FS-PA; without reliability 342 adjustment), and 2S-PA. For JSEM, we used the *lavaan* package (Rosseel, 2012) in R to fit a full SEM 343 model with partial invariance using all indicators, with identification constraints such that the grand 344 variances of η_M and η_Y were unity. Diagonally weighted least squares (DWLS) was used as the model 345 included both continuous and binary indicators. For FS-PA and 2S-PA, we first used lavaan and a 346 multiple-group CFA (with maximum likelihood estimation) to obtain the regression factor scores for η_M , 347 denoted as $\tilde{\eta}_M$, and then used the *mirt* R package (Chalmers, 2012) and a multiple-group two-parameter 348 logistic item response model (with maximum likelihood estimation) to obtain the expected a posteriori 349 (EAP) scores for η_Y , denoted as $\tilde{\eta}_Y$. For 2S-PA, reliability estimates, $\tilde{\rho}_{\tilde{\eta}_Y i}$ and $\tilde{\rho}_{\tilde{\eta}_M i}$, were computed using 350 $1 - SE^2(\tilde{\eta}_i)/Var(\eta)$, where $SE(\tilde{\eta}_i)$ is the case-specific standard error of the EAP score, available from *mirt*. 351 Similar to multiple-group SEM, in the item response models, the loadings and thresholds were constrained 352 equal for the invariant items but free for the noninvariant items, so the latent factor was on the same 353 metric. In both JSEM and the first stages of FS-PA and 2S-PA, we specified the correct partial invariance 354 models (but without the unique covariances). We deliberately used two separate programs for 2S-PA to 355 demonstrate its flexibility. In the second stage, we used OpenMx with the measurement model 356

$$\begin{split} \tilde{\eta}_{Mi} &= \eta_{Mi} + e_{\tilde{\eta}_{Mi}} \\ \tilde{\eta}_{Yi} &= \eta_{Yi} + e_{\tilde{\eta}_{Yi}} \end{split},$$

357 the constraints

$$\begin{split} \tilde{\rho}_{\tilde{\eta}_{M}i} \operatorname{Var}(e_{\tilde{\eta}_{M}i}) &= (1 - \tilde{\rho}_{\tilde{\eta}_{M}i}) \operatorname{Var}(\eta_{M}) \\ \tilde{\rho}_{\tilde{\eta}_{Y}i} \operatorname{Var}(e_{\tilde{\eta}_{Yi}}) &= (1 - \tilde{\rho}_{\tilde{\eta}_{Y}i}) \operatorname{Var}(\eta_{Y}) \end{split}$$

358 and the structural model

$$\eta_M = \alpha_M + \alpha_1 G + \beta_1 X + \zeta_M$$
$$\eta_Y = \alpha_Y + \alpha_2 G + \beta_2 X + \beta_3 \eta_M + \zeta_Y$$

The inclusion of $\alpha_1 G$ and $\alpha_2 G$ accounted for the intercept differences across groups.

For all three approaches, we obtained the standardized coefficients for the β_1 , β_2 , β_3 paths, as well as the product term $\beta_1\beta_3$ (i.e., the standardized indirect effect). With JSEM, the corresponding 95% CIs were obtained using the delta method for β_1 to β_3 , and the Monte Carlo method (MacKinnon et al., 2004) for $\beta_1\beta_3$; with 2S-PA, CIs were obtained using the profile likelihood method (Pek & Wu, 2015). The analytic approaches were compared based on the convergence rate, bias, RMSE, and 95% CI coverage. We also evaluated the statistical power based on the proportion of replications where the 95% CI excludes zero for conditions with nonzero indirect effects.

367 **Results**

368 Convergence

Convergence was 100% for all conditions with FS-PA. When n = 50, convergence was substantially better for 2S-PA (89.80%) than for JSEM (8.29%). When $n \ge 100$, 2S-PA had 100% convergence, but JSEM still had convergence issues (32.56%). JSEM had 82.49% convergence when n = 300, and 99.66% when n = 1,000. The main reason for nonconvergence in 2S-PA was failures in computing factor scores or the corresponding reliability in the first stage due to negative latent or error variance estimates, whereas it was empirical unidentifiability due to near-perfect or near-zero associations among indicators for JSEM.

375 **Bias**

Figure 3 shows the bias in estimating the β s and the indirect effect. All three methods estimated coefficients that are truly zero with little bias. When the true coefficients were nonzero, FS-PA, ignoring measurement error, produced biased estimates for virtually all coefficients (bias between -0.117 and 0.014). Both 2S-PA and JSEM performed better with a larger *n*; with a small n = 50, 2S-PA (bias between -0.066 and -0.026) generally performed better than JSEM (bias between -0.240 and 0.116), especially for β_2 and β_3 .

382 **RMSE**

Figure 4 shows the RMSE of the different methods, which combines both bias and (in)efficiency of the estimates. The RMSEs for FS-PA were the smallest for small-sample conditions, especially when there could be little attenuation due to measurement error; however, FS-PA performed worst in larger samples for nonzero coefficients. For all of the β coefficients and the indirect effect, 2S-PA generally provided better RMSEs than JSEM, especially in small samples. When *n* reaches 300, the RMSEs were comparable for 2S-PA and JSEM.

389 Coverage

Figure 5 shows the coverage of 95% CI for 2S-PA and JSEM; coverage for FS-PA was bad for nonzero coefficients due to parameter bias (close to 0.00 for β_3 and $\beta_1\beta_3$ when n = 1,000), and was excluded from the graph. 2S-PA showed coverage close to 95% for almost all conditions and parameters, except for some undercoverage when estimating zero β_3 in small samples. JSEM generally had worse coverage than 2S-PA, which also corresponded to severely inflated Type I error rates (i.e., 1 - coverage rate when true coefficient = 0) of up to 0.34 when n = 50 for β_3 , whereas 2S-PA had Type I error rates < 0.06 for all conditions and coefficients.

397 Power

Figure 6 shows the empirical power, calculated as the rates in which the 95% CI excluded zero when making inferences on coefficients that are truly nonzero. Power was generally similar for FS-PA and 2S-PA, while JSEM had higher power for β_1 , β_2 , and β_3 with small samples (but at the cost of higher Type I error rates). When $n \ge 100$, the empirical power was similar for all three approaches.

In summary, with a more complex data generating model, we found 2S-PA to have substantially fewer convergence issues than JSEM, and it mostly outperforms JSEM in parameter estimation and inference, especially in small samples.

405

Empirical Example

In this section, we demonstrate 2S-PA as well as PA, FS-PA, and the JSEM approaches, using empirical data made publicly available by Lui (2019) on the Open Science Framework

(https://osf.io/93qpt/). Data were collected in 2018 from 1,148 undergraduate students, aged 18 or older,

⁴⁰⁹ in a private university. Lui evaluated measurement invariance of the College Life Alcohol Salience Scale

(CLASS; Osberg et al., 2010), which measures individuals' college-related alcohol beliefs, across different

⁴¹¹ sociodemographic subgroups, including ethnicity. Subsequently, CLASS was used to predict students'

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⁴¹² alcohol consumption and drinking problems, measured by the Alcohol Use Disorders Identification Test
⁴¹³ (AUDIT; Saunders et al., 1993). While meeting scalar invariance across most grouping variables, CLASS
⁴¹⁴ showed partial scalar invariance across ethnicity. For pedagogical purposes, we focus on analyzing the
⁴¹⁵ relationship between college-related alcohol beliefs and drinking problems across ethnic groups in this
⁴¹⁶ demonstration.

⁴¹⁷ CLASS contains fifteen 5-point Likert items (1 = strongly disagree and 5 = strongly agree). Seven ⁴¹⁸ of the ten items of AUDIT measure negative alcohol-related consequences, i.e., drinking problems, on a ⁴¹⁹ variety of 3-to-5-point scales.³ Study participants were domestic students of European American (44.9%), ⁴²⁰ Asian American (19.9%), African American (10.3%), Latinx American (16.7%), and mixed or other ethnic ⁴²¹ backgrounds (8.3%).

We assess configural, metric, and scalar invariance of CLASS and AUDIT, respectively, using 422 lavaan (Rosseel, 2012) with maximum likelihood estimation. If a more constrained model has a worse fit 423 than a less constrained model, indicating invariance violations, we use sequential specification search (Yoon 424 & Kim, 2014) to identify and free noninvariant parameters, until arriving at a partial invariance model. 425 After establishing scalar or partial scalar invariance, we predict drinking problems with college alcohol 426 beliefs using five approaches: (a) PA, (b) FS-PA, (c) JSEM, and (d) 2S-PA with regression scores, and (e) 427 2S-PA with Bartlett scores. With (a), we model the relationship between CLASS and AUDIT with their 428 sum scores and ethnicity as a covariate. Sum score PA does not account for measurement noninvariance 429 nor unreliability. With (b), we first obtain the regression factor scores of CLASS and AUDIT from a 430 multigroup CFA. We then use the regression factor scores in a path model with ethnicity as a covariate. 431 Measurement noninvariance, if identified, is adjusted in the first step, whereas measurement unreliability is 432 not accounted for in FS-PA. With (c), we perform multiple-group SEM that includes a structural path 433 between the two latent factors, with scalar or partial scalar models for CLASS and AUDIT. Thus, JSEM 434 accounts for both measurement unreliability and noninvariance in one model. With (d) and (e), in the first 435 stage, we obtain the factor scores from the scalar or partial scalar models and compute the reliability of the 436 factor scores as shown in Table 1. Partial invariance is accounted for in the first stage. In the second stage, 437 we treated the factor scores as indicators of the latent variables with known reliability. We compare the 438 standardized path coefficients using the grand SD among the five approaches. 439

Details of the measurement invariance test results are provided in the supplemental materials. We replicated the findings of Lui (2019) for CLASS and concluded with a partial scalar model by freeing 10

 $^{^{3}}$ As reported in Lui (2019), items 4 to 10 of AUDIT measure drinking problems; items 4, 6, and 8 are on a scale of 0-4, items 5 and 7 are on a scale of 0-3, and items 9 and 10 consists of three response categories (0, 2, and 4).

intercept equality constraints across four ethnic groups (European American, Asian American, African American, Latinx American). For AUDIT, we first established partial metric invariance by freeing four loading equality constraints and concluded with a partial scalar model by additionally freeing four intercept equality constraints. The reliability of the composite and factor scores was similarly high for CLASS ($\tilde{\rho} =$.92, .92, .87, .91) and satisfactory for AUDIT ($\tilde{\rho} = .79, .79, .87, .78$), using formulas from Table 1.

⁴⁴⁷ Consistent with the results in Lui (2019), we found that higher college alcohol beliefs predicted ⁴⁴⁸ more drinking problems in all three approaches (all ps < .001). Among the five approaches, FS-PA yielded ⁴⁴⁹ the smallest standardized coefficient of AUDIT on CLASS ($\hat{\beta} = 0.49, 95\%$ CI [0.44, 0.54]), followed by ⁴⁵⁰ sum-score PA ($\hat{\beta} = 0.54, 95\%$ CI [0.49, 0.58]). 2S-PA with regression scores ($\hat{\beta} = 0.59, 95\%$ CI [0.53, 0.65]) ⁴⁵¹ and 2S-PA with Bartlett scores ($\hat{\beta} = 0.59, 95\%$ CI [0.52, 0.65]) resulted in a similar standardized path ⁴⁵² coefficient as JSEM ($\hat{\beta} = 0.60, 95\%$ CI [0.54, 0.65]).

As shown in this example, consistent with our simulation results, using composite or factor scores without adjusting for unreliability resulted in a smaller standardized path coefficient. On the other hand, both 2S-PA and JSEM yielded a larger coefficient as well as wider CIs.

456

Discussion

In behavioral sciences, measured variables are prone to random and systematic errors. To account 457 for these errors, the methodological literature generally regards joint modeling of measurement and 458 structural models as the gold standard. While joint modeling is flexible, it is not always the most 459 convenient for applied researchers, who usually treat construct operationalization and statistical analyses 460 as two separate processes. Furthermore, joint modeling usually means dealing with many variables 461 simultaneously, even when researchers have a relatively simple conceptual model, which presents many 462 computational and practical challenges. As a result, while joint modeling is a gold standard in theory, 463 applied researchers still use composite scores when analyzing their conceptual models in practice. 464

A salient example of the above problem, which is also the focus of the current paper, can be found in analyses involving composite scores that are potentially noninvariant across groups. While methodological guidelines are clear that joint modeling should be used if measures show only partial invariance across groups, from our observation and a small literature review, applied researchers continue to use composite scores following measurement invariance analysis. However, as is well known in the methodological literature, using composite scores ignores random and systematic errors and thus leads to biased parameter estimates and invalid inferences.

472

As an alternative to joint SEM modeling, we suggest that researchers use 2S-PA to analyze their

conceptual models by obtaining factor scores and then adjusting for measurement errors using estimates of 473 observation-specific reliability of those factor scores. We recommend using 2S-PA with factor scores over 474 JSEM in analysis with discrete indicators, moderate sample size (< 1,000), and moderate reliability of the 475 factor scores (similar to the values in our Study 2). For analysis with continuous indicators, we recommend 476 using 2S-PA with sum scores when the sample size is small (e.g., < 400 per group) and when the composite 477 reliability is low (e.g., < .70 in any groups). Results of two simulation studies show that 2S-PA gives 478 comparable estimates as JSEM in relatively simple models and large sample sizes, has better control of 479 Type I error rates, and has substantially fewer convergence problems in complex models with categorical 480 indicators. While the most complex model in our studies only has three latent variables, we expect the 481 advantage of 2S-PA over joint modeling to be even more striking for models with more latent variables. 482

Although the current paper focuses solely on applying 2S-PA for adjusted inferences following 483 multiple-group measurement invariance analyses, we also want to acknowledge other developed two-stage 484 approaches that tackle similar problems. For example, when all indicators are continuous with 485 homogeneous measurement error variances within a group, the within-group reliability of composite or 486 factor scores is constant. One can thus use a multiple-group version of the reliability adjustment method 487 discussed in Hsiao et al. (2018) and Savalei (2019) in any SEM software without constraint/definition 488 variables, which is similar to 2S-PA with composite scores in Study 1 but uses a multi-group model. 489 Another promising line of research is the Structural After Measurement (SAM) approach (Rosseel & Loh, 490 2021). With SAM, one obtains measurement parameter estimates (e.g., loadings and intercepts, instead of 491 factor scores) from separate measurement models of the latent constructs and uses those measurement 492 parameters to obtain corrected estimates of structural coefficients. It subsumes two-stage methods such as 493 factor score regression and path analysis with Croon (2002)'s corrections and was recently added to the R 494 package lavaan. At the time of writing, however, SAM supports neither equality constraints of structural 495 coefficients across groups nor analyses with categorical indicators, so we could not include it for 496 comparisons in our simulation studies. As 2S-PA, SAM, and other two-stage methods continue to evolve, 497 future research can compare and integrate these approaches. 498

When using 2S-PA and other two-stage estimation methods, one consideration is whether one can obtain factor scores in separate measurement models for different constructs in the structural model. In the current paper, as in M. H. C. Lai and Hsiao (2021), we assume that the indicators follow an independent cluster structure, meaning that each indicator is directly associated with only one latent construct, which allows us to separate the measurement models into chunks. When there are cross-loadings or unique covariances between indicators of different constructs, the separation strategy is more robust as it reduces

the influence of omitting these crossed paths on the structural parameter estimation, compared to joint 505 modeling that omits these crossed paths (M. H. C. Lai & Hsiao, 2021). However, neither the separation 506 strategy nor omitting the cross paths in JSEM gives consistent structural parameter estimates (Hayes & 507 Usami, 2020); instead, a theoretically valid approach is to use a JSEM model that correctly specifies the 508 cross-loadings and unique covariances. An extension of 2S-PA for handling cross paths in measurement 509 models would obtain factor scores from models with multiple latent constructs. In addition to computing 510 case-specific reliability estimates, one also needs the case-specific loadings and covariances of the factor 511 scores, and in the second stage, the factor scores are treated as indicators of the latent constructs but with 512 loadings and error covariances constrained based on the values obtained in the first stage. Such an 513 approach can be further explored in future studies. 514

The current paper also shows that obtaining standardized coefficients for analyses involving 515 multiple samples or subgroups is not trivial. When researchers use multiple-group analyses, popular SEM 516 software such as *OpenMx*, *Mplus*, and *lavaan* performs standardization using the group-specific SDs. 517 However, researchers can also use single-group analyses on the pooled data with dummy-coded grouping 518 variables for group membership, as is the case in the 2S-PA methods we examined in this paper and in 519 multiple-indicator multiple-cause models (e.g., Bauer, 2017). As we illustrated, the grand standard 520 deviation is typically used to obtain standardized coefficients with the single-group approach, which is not 521 comparable to those in multiple-group analyses. In our opinion, grand standardization is more appropriate 522 as it preserves ordering and equality constraints on the unstandardized coefficients; standardization using 523 group-specific SDs generally leads to unequal coefficients even when the path coefficients are constrained to 524 equal in the model. An alternative is to use the pooled within-group SD, which also preserves ordering and 525 equality constraints as each coefficient is scaled by the same number across groups.⁴ Both applied and 526 methodological work should be mindful that different analytic approaches and standardization strategies 527 may yield incomparable coefficients across studies, and future research can further explore the pros and 528 cons of different standardization options. 529

Given that 2S-PA is relatively new, many opportunities exist to address its current limitations in future studies. We highlight a few major ones here. First, in the current implementation of 2S-PA, the second-stage likelihood function assumes that the measurement error of the factor scores is normally distributed. Such an assumption holds when normality is assumed in the measurement models, as in factor analysis assuming normality; however, the sampling distribution of factor scores only approaches normality in large samples for measurement models with categorical indicators. Even though the current simulation

 $^{^4}$ This is commonly done when computing Cohen's d effect size.

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results show 2S-PA to still perform reasonably well in small samples with categorical indicators, future
research can (a) investigate situations with more complex first-stage measurement models, which may take
larger samples to achieve asymptotic normality, and (b) extend the likelihood functions in the second stage
of 2S-PA to accommodate nonnormality. One specific direction is to examine the performance of robust
standard errors (e.g., with sandwich estimators or resampling methods; see K. Lai, 2019, for an overview).

Second, while our simulation Study 2 only focused on expected a posteriori factor scores, future 541 research should explore the performance of 2S-PA with other types of factor scores for categorical 542 indicators (e.g., maximum a posteriori scores, maximum likelihood estimates, etc; see Estabrook & Neale, 543 2013). Based on the theory of 2S-PA, the estimated scores should be consistent estimates for the latent 544 variables, have an approximately normal sampling distribution, and have consistent estimates of sampling 545 variability available. Third, although 2S-PA uses a simplified structural model, users still need to specify 546 the required constraints to set the reliability of factor scores and obtain standardized coefficients. We are 547 currently working on providing R scripts to automate some of these steps. Fourth, future research can 548 extend 2S-PA to models researchers routinely use, such as models with latent interactions and multilevel 549 models. Finally, for the second-stage estimation, alternative estimators, such as Bayesian, least squares, 550 and generalized method of moments estimators, can be explored. 551

In conclusion, the current paper shows how researchers can account for measurement quality—both measurement invariance and measurement reliability—using two-stage path analysis with each construct operationalized by a factor score variable. We show that two-stage path analysis can be a viable option, especially in small samples or when the number of measurement indicators is too big to deal with practically. While it is good to see more empirical research reporting on measurement invariance and reliability, we recommend researchers take the necessary next step: incorporate both partial invariance and unreliability in their main statistical analyses to obtain more valid results.

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Table 1

Three Types of Estimated Scores and the Corresponding Reliability.

	Loading on		
Estimated	latent variable		
scores Scoring matrix (\mathbf{A}_g)	(λ_g^*)	$\mathrm{Var}(\tilde{\eta})$	Reliability $(\rho_{\tilde{\eta}})$
$\overline{\text{Regression}} \psi_g \boldsymbol{\lambda}_g^{T} \boldsymbol{\Sigma}_g^{-1}$	$\psi_{g} \boldsymbol{\lambda}_{g}^{ op} \boldsymbol{\Sigma}_{yg}^{-1} \boldsymbol{\lambda}_{g}$	$\psi_g^2 oldsymbol{\lambda}_g^ op oldsymbol{\Sigma}_{yg}^{-1} oldsymbol{\lambda}_g$	$\psi_g \boldsymbol{\lambda}_g^{\top} \boldsymbol{\Sigma}_g^{-1} \boldsymbol{\lambda}_g$
Bartlett $(\boldsymbol{\lambda}_{g}^{T}\boldsymbol{\Theta}_{g}^{-1}\boldsymbol{\lambda}_{g})^{-1}\boldsymbol{\lambda}_{g}^{T}\boldsymbol{\Theta}_{g}^{-1}$	1	$\boldsymbol{\psi} + (\boldsymbol{\lambda}_{g}^{\top}\boldsymbol{\Theta}_{g}^{-1}\boldsymbol{\lambda}_{g})^{-1}$	$\frac{\Psi}{\Psi + (\boldsymbol{\lambda}_{g}^{T}\boldsymbol{\Theta}_{g}^{-1}\boldsymbol{\lambda}_{g})^{-1}} (1^{T}\boldsymbol{\lambda}_{g})^{2}\Psi}$
Sum 1^{T}	$1^{ op} \mathbf{\lambda}_{g}$	$(1^{T} \boldsymbol{\lambda}_g)^2 \boldsymbol{\psi} + 1^{T} \boldsymbol{\Theta}_g 1$	$\frac{(1^{T}\boldsymbol{\lambda}_g)^2\boldsymbol{\psi}}{(1^{T}\boldsymbol{\lambda}_g)^2\boldsymbol{\psi} + 1^{T}\boldsymbol{\Theta}_g1}$
score			_ 0

						Bias							RMSE			
β_1	З	n_1, n_2	PA	FS-PA	Croon	JSEM	$2S-PA_1$	$2S-PA_2$	$2S-PA_3$	PA	FS-PA	Croon	JSEM	$2S-PA_1$	$2S-PA_2$	$2S-PA_3$
0	.49, .61	50, 30	-0.001	-0.001	0.000	-0.001	0.000	-0.001	0.000	0.115	0.118	0.139	0.163	0.143	0.148	0.152
		100, 60	0.004	0.005	0.005	0.006	0.007	0.006	0.006	0.079	0.079	0.096	0.103	0.098	0.101	0.103
		500, 300	0.001	0.002	0.002	0.002	0.002	0.002	0.002	0.035	0.035	0.044	0.044	0.044	0.045	0.045
		1000, 600	0.000	0.000	0.000	0.001	0.001	0.001	0.000	0.025	0.025	0.032	0.032	0.032	0.032	0.033
	.71, .77	50, 30	-0.003	-0.005	-0.005	-0.006	-0.005	-0.005	-0.004	0.115	0.116	0.128	0.137	0.130	0.133	0.133
		100, 60	0.005	0.006	0.006	0.007	0.007	0.007	0.006	0.080	0.080	0.090	0.092	0.090	0.092	0.092
		500, 300	0.001	0.002	0.002	0.002	0.002	0.002	0.002	0.035	0.035	0.039	0.040	0.040	0.040	0.040
		1000, 600	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.025	0.025	0.028	0.028	0.028	0.029	0.029
0.54	.49, .61	50, 30	-0.122	-0.151	-0.087	0.015	-0.073	-0.061	-0.010	0.166	0.197	0.172	0.773	0.196	0.178	0.146
		100, 60	-0.119	-0.129	-0.043	-0.001	-0.033	-0.019	-0.001	0.142	0.153	0.107	0.102	0.107	0.112	0.098
		500, 300	-0.120	-0.121	-0.018	-0.005	-0.013	-0.002	0.003	0.125	0.126	0.047	0.043	0.044	0.046	0.042
		1000, 600	-0.121	-0.121	-0.017	-0.007	-0.012	-0.001	0.002	0.123	0.124	0.035	0.032	0.033	0.033	0.031
	.71, .77	50, 30	-0.076	-0.082	-0.035	-0.010	-0.030	-0.020	-0.009	0.134	0.141	0.130	0.131	0.131	0.134	0.125
		100, 60	-0.065	-0.066	-0.011	0.002	-0.007	0.002	0.004	0.102	0.103	0.087	0.088	0.087	0.090	0.087
		500, 300	-0.068	-0.066	-0.005	-0.002	-0.003	0.004	0.002	0.076	0.074	0.038	0.037	0.037	0.039	0.037
		1000, 600	-0.068	-0.066	-0.005	-0.003	-0.003	0.004	0.002	0.073	0.070	0.027	0.027	0.027	0.028	0.027
0	.49, .61	40, 40	-0.002	0.000	0.000	0.000	-0.002	0.000	0.000	0.114	0.117	0.136	0.157	0.153	0.144	0.145
		80, 80	0.003	0.003	0.004	0.004	0.004	0.003	0.003	0.081	0.081	0.098	0.104	0.103	0.102	0.103
		400, 400	0.002	0.002	0.002	0.002	0.002	0.002	0.002	0.035	0.036	0.044	0.044	0.044	0.045	0.045
		800, 800	0.000	0.000	0.000	0.000	0.000	0.000	0.001	0.025	0.025	0.031	0.031	0.031	0.032	0.032
	.71, .77	40, 40	-0.005	-0.005	-0.005	-0.006	-0.005	-0.005	-0.006	0.113	0.115	0.126	0.134	0.128	0.130	0.130
		80, 80	0.004	0.004	0.005	0.005	0.005	0.005	0.005	0.080	0.080	0.089	0.091	0.089	0.091	0.091
		400, 400	0.001	0.001	0.001	0.001	0.001	0.001	0.001	0.035	0.035	0.040	0.040	0.040	0.040	0.040
		800, 800	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.025	0.025	0.028	0.028	0.028	0.028	0.029
0.56	.49, .61	40, 40	-0.120	-0.143	-0.082	-0.006	-0.064	-0.056	-0.018	0.163	0.186	0.160	0.150	0.163	0.165	0.149
		80, 80	-0.114	-0.123	-0.039	0.000	-0.027	-0.017	-0.003	0.140	0.148	0.106	0.101	0.112	0.109	0.098
		400, 400	-0.115	-0.114	-0.016	-0.004	-0.011	0.000	0.002	0.120	0.120	0.045	0.043	0.044	0.046	0.042
		800, 800	-0.115	-0.114	-0.014	-0.005	-0.009	0.001	0.002	0.118	0.117	0.033	0.030	0.031	0.032	0.030
	.71, .77	40, 40	-0.075	-0.080	-0.036	-0.011	-0.030	-0.021	-0.012	0.134	0.138	0.127	0.127	0.128	0.130	0.123
		80, 80	-0.063	-0.064	-0.011	0.002	-0.007	0.001	0.003	0.101	0.102	0.087	0.087	0.087	0.089	0.087
		400, 400	-0.065	-0.063	-0.005	-0.002	-0.003	0.004	0.002	0.074	0.071	0.038	0.038	0.038	0.039	0.038
		800, 800	-0.066	-0.063	-0.004	-0.002	-0.003	0.004	0.002	0.070	0.067	0.027	0.027	0.027	0.028	0.027

Note. The best performing method for each condition was indicated in bold fonts. $2S-PA_1 = two-stage$ path analysis with regression factor scores. $2S-PA_2 = two-stage path analysis with Bartlett factor scores. <math>2S-PA_3 = two-stage path analysis with sum scores.$

Table 2Results of Study 1 (Bias and RMSE)

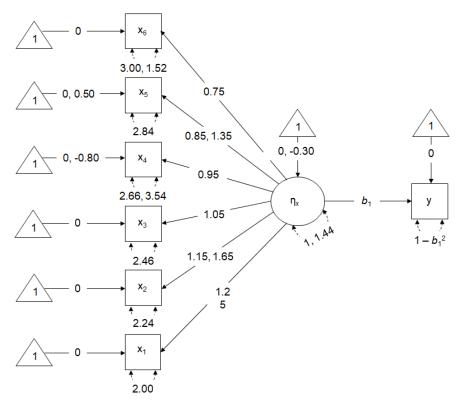
Table 3Results 0	3 s of Stud	Table 3 Results of Study 1 (SE Bias and Coverage)	sias and	Coverag	le)						
					Rel	Relative SE Bias $(\%)$	3ias (%)				
β_1	8	n_1, n_2	\mathbf{PA}	FS-PA	Croon	JSEM	$2S-PA_1$	$2S-PA_2$	n_1, n_2 PA FS-PA Croon JSEM 2S-PA ₁ 2S-PA ₂ 2S-PA ₃ PA FS-PA	\mathbf{PA}	FS-PA
c	10 01		000	010	5	10 00	001	1 00	10.0		010

					~											
β_1	0)	n_1, n_2	\mathbf{PA}	FS-PA	Croon	JSEM	$2S-PA_1$	$2S-PA_2$	$2S-PA_3$	\mathbf{PA}	FS-PA	Croon	JSEM	$2S-PA_1$	$2S-PA_2$	$2S-PA_3$
0	.49, .61	50, 30	-2.99	-3.53	-2.71	-13.00	-4.08	-4.89	-3.01	94.1	94.2	94.6	90.72	94.2	94.2	94.0
		100, 60	0.38	1.78	2.22	-2.37	1.64	0.93	0.17	95.0	95.2	95.1	94.0	95.2	95.2	94.9
		500, 300	2.22	2.60	2.06	1.92	2.51	2.47	2.06	94.8	94.7	94.6	94.4	94.5	94.5	95.0
		1000, 600	0.27	0.49	-0.16	0.01	0.50	0.42	0.32	95.3	95.6	95.4	95.4	95.5	95.5	95.4
	.71, .77	50, 30	-2.27	-3.02	-1.13	-7.30	-3.25	-3.80	-2.68	94.5	93.8	94.5	92.08	93.8	93.8	94.4
		100, 60	-0.13	0.03	0.69	-1.68	-0.08	-0.39	-0.35	94.9	94.8	95.1	94.3	94.9	94.9	95.1
		500, 300	1.81	2.25	2.35	1.92	2.21	2.17	1.84	95.0	95.0	95.0	94.8	94.9	94.8	95.0
		1000, 600	0.75	0.95	1.01	0.70	0.93	0.88	0.72	95.2	95.6	95.4	95.5	95.6	95.6	95.1
0.54	.49, .61	50, 30	-3.06	-10.75	-13.14	-71.91	-25.83	-20.66	-3.92	81.04	73.20	85.36	90.60	87.64	85.40	94.0
		100, 60	-1.32	-3.19	-5.49	-5.49	-5.03	-13.17	0.85	69.12	64.12	90.92	94.2	92.5	91.16	95.2
		500, 300	2.28	0.55	-2.14	0.91	2.87	-6.55	6.05	7.12	7.16	92.36	94.9	94.9	93.7	96.4
		1000, 600	-1.02	-2.37	-4.63	-2.19	-0.19	-8.31	2.80	0.28	0.32	90.12	94.0	93.7	92.9	95.3
	.71, .77	50, 30	-2.75	-5.34	-7.57	-7.89	-4.87	-12.50	-1.11	89.40	87.92	92.7	92.7	93.7	91.92	95.6
		100, 60	-2.12	-2.59	-5.62	-3.06	-0.61	-8.37	0.65	85.96	86.64	93.4	94.1	94.5	92.8	94.8
		500, 300	2.11	1.84	-1.85	2.02	4.47	-3.70	5.36	51.08	53.92	94.0	95.4	96.0	94.4	96.4
		1000, 600	-0.06	-0.50	-3.88	-0.21	1.83	-5.92	2.97	21.72	25.04	94.2	95.3	95.6	93.4	95.7
0	.49, .61	40, 40	-2.39	-3.16	-1.78	-11.26	-9.16	-4.14	-2.35	94.3	94.1	94.8	91.36	94.0	93.9	94.8
		80, 80	-1.68	-1.39	-1.27	-4.98	-3.58	-1.86	-1.92	94.8	95.1	95.1	93.6	95.1	95.1	94.9
		400, 400	0.71	1.01	0.50	0.32	0.93	0.86	0.62	95.5	95.2	95.0	95.0	95.1	95.0	95.3
		800, 800	1.28	1.40	1.07	1.07	1.43	1.42	1.20	95.8	95.5	95.8	95.4	95.5	95.6	95.7
	.71, .77	40, 40	-1.27	-1.95	-0.03	-5.71	-2.05	-2.58	-1.84	95.0	94.3	95.0	93.3	94.3	94.2	94.6
		80, 80	-0.58	-0.35	0.51	-1.93	-0.33	-0.57	-0.54	94.7	95.1	95.2	94.6	95.2	95.3	94.8
		400, 400	0.87	1.10	1.20	0.73	1.09	1.05	0.87	95.5	95.8	95.5	95.4	95.7	95.7	95.6
		800, 800	0.32	0.88	0.99	0.68	0.88	0.88	0.33	95.2	95.4	95.4	95.3	95.4	95.4	95.2
0.56	.49, .61	40, 40	-0.99	-5.43	-8.17	-9.51	-9.84	-16.14	-7.49	81.68	75.28	87.04	92.40	89.64	87.44	94.6
		80, 80	-3.68	-4.96	-7.88	-5.69	-10.65	-13.27	-0.41	69.64	67.08	91.24	93.4	92.6	91.48	94.6
		400, 400	0.37	-0.89	-3.74	-1.16	0.47	-8.12	3.21	10.08	10.92	92.28	94.5	94.6	93.0	96.0
			0.95	-0.58	-3.06	0.18	2.05	-6.34	4.82	0.64	0.60	92.20	94.8	94.9	93.6	95.9
	.71, .77		-2.29	-3.66	-6.21	-5.44	-3.08	-10.43	-0.40	89.08	88.28	92.6	92.8	93.7	92.00	94.7
			-2.54	-3.24	-6.52	-3.18	-0.96	-8.79	0.37	86.56	86.36	93.3	94.6	94.4	92.5	95.5
		400, 400	0.87	0.70	-3.31	0.77	3.15	-4.74	4.03	55.00	58.36	93.8	95.1	95.6	93.9	96.0
		800, 800	-0.49	-0.32	-4.17	-0.10	2.19	-5.65	2.47	25.44	28.60	93.8	94.9	95.7	93.8	95.4

Note. Suppoint values are indicated in italic fonts (|RSB| > 10% or coverage < 92.5%). 2S-PA₁ = two-stage path analysis with regression factor scores. $2S-PA_2 = two-stage$ path analysis with Bartlett factor scores. $2S-PA_3 = two-stage$ path analysis with sum scores.

Figure 1

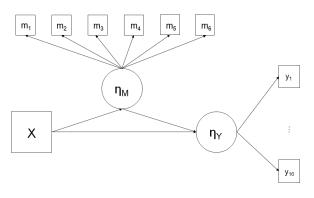
Data generating model for Study 1.



Note. Group-specific parameter values are separated by a comma. The loading values shown in the graph are for the moderate-reliability conditions; they were .45 to .95 for Group 1 in the low-reliability conditions.

Figure 2

Data generating model for Study 2.



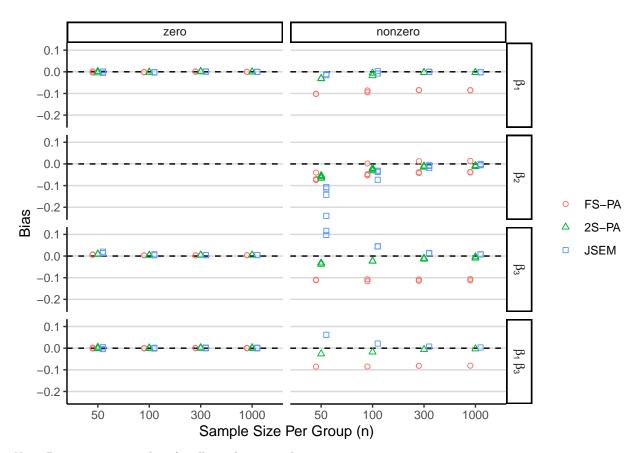


Figure 3

Bias in Parameter Estimates for Study 2

Note. Points represent values for all simulation conditions.

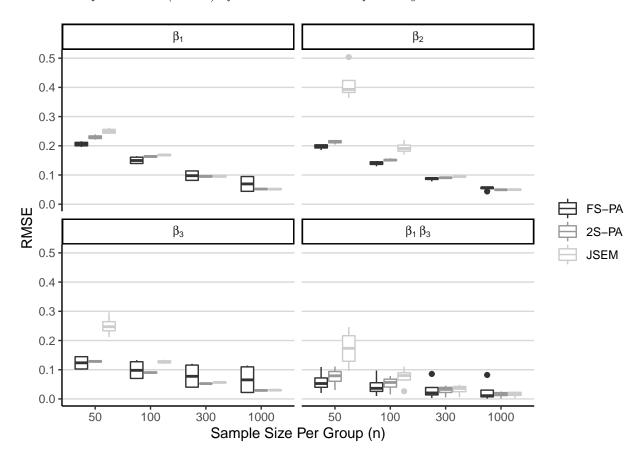


Figure 4

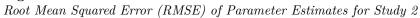
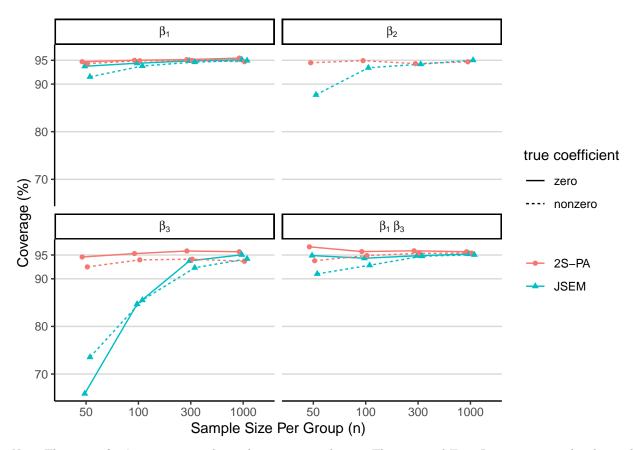
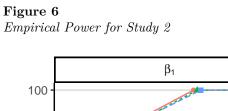


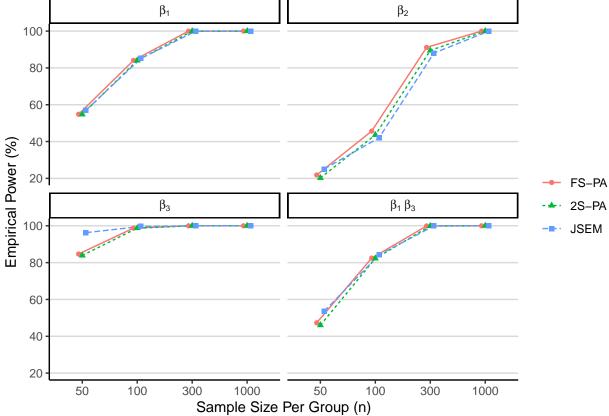
Figure 5

Coverage of 95% Confidence Intervals for Study 2



Note. The points for β_2 represent median values across conditions. The empirical Type I error rates can be obtained as 1 - coverage rate when the true coefficient is zero.





Note. The points for β_2 represent median values across conditions.